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Control of mechanotransduction by molecular clutch dynamics

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Abstract

The linkage of cells to their microenvironment is mediated by a series of bonds that dynamically engage and disengage, in what has been conceptualized as the molecular clutch model. Whereas this model has long been employed to describe actin cytoskeleton and cell migration dynamics, it has recently been proposed to also explain mechanotransduction, i.e. the process by which cells convert mechanical signals from their environment into biochemical signals. Here we review the current understanding on how cell dynamics and mechanotransduction are driven by molecular clutch dynamics and its master regulator, the force loading rate. Throughout the review, we place a specific emphasis on the quantitative prediction of cell response enabled by combined experimental and theoretical approaches.

21 **The molecular clutch hypothesis: a means to conceptualize cell adhesion dynamics.**

22 Cells in almost any physiological setting, from bacteria infecting a tissue to neurons within
23 the brain, are constantly exerting mechanical forces and transmitting them to neighboring
24 cells and the extracellular matrix (ECM) [1-3]. These forces direct cell functions such as
25 differentiation [4] or migration [5], and drive processes in development [6], cancer [7], the
26 physiology of the cardiovascular system [8], and several other scenarios in health and
27 disease. Unravelling the mechanisms and implications of these mechanical interactions
28 requires the understanding of how cells exert forces, how those are transmitted to the cell
29 microenvironment, and how they trigger downstream events affecting cell function. In most
30 eukaryotic settings, cells exert forces largely through actin polymerization, and the
31 contraction of the actin cytoskeleton by myosin molecular motors. Once force is exerted to
32 actin, it is transmitted first to a series of **adaptor proteins** (see glossary) linked to actin, and
33 then to transmembrane proteins linking adaptor proteins to the cell microenvironment (Fig.
34 1). These transmembrane proteins consist mostly of integrins (which bind to the ECM) [9]
35 and cadherins (which bind to neighboring cells) [10], and the molecular assemblies
36 composed of actin, adaptor proteins, and integrins or cadherins are known respectively as
37 cell-matrix or cell-cell adhesion complexes.

38 From actin to integrins/cadherins, adhesion complexes exhibit a precise spatial molecular
39 organization [11, 12], and are responsible for the specific adhesion of cells to their
40 environment, which is otherwise dominated by non-specific repulsive interactions [13]. A
41 fundamental aspect of adhesion complexes is that they are extremely dynamic. Myosin-
42 powered **contractility**, and actin polymerization pushing against the membrane [14, 15],
43 drive a constant flow of actin, generally termed “**retrograde flow**” because it moves from
44 the cell edge where cell-ECM adhesions form towards the cell center [16, 17]. This flow
45 (which can be observed for different types of actin structures, from lamellipodia to stress
46 fibers) is only partially transmitted to adaptor proteins and integrins, leading to
47 progressively slower retrograde speeds as the molecules get closer to the ECM [18, 19].
48 Even though they are far less characterized, similar flows apply in cadherin-based cell-cell
49 adhesions [20], and even non-actin based systems [21]. This progressively reduced flow
50 points at a dynamic formation and release of bonds between the different molecular
51 elements, which only transmit movement (and force) when the system is engaged.
52 Consistently, retrograde flows inversely correlate with cell migration speed [14, 16, 22]. This
53 suggests that when the system is engaged, force transmitted to the ECM counters myosin
54 contractility, slowing actin retrograde flow (as observed for instance in fish keratocytes [23])
55 and fostering actin protrusion away from the cell center. The dynamic nature of the
56 cytoskeleton-ECM linkage, and its relationship to cell movement, led Mitchison and
57 Kirschner [24] to introduce the term “**molecular clutch**” to describe it, in an analogy to the
58 dynamic linkage between different shafts of a mechanical engine.

59 Because it regulates both force transmission and cell movement, this molecular clutch
60 between actin and the ECM (or neighboring cells) controls the mechanical balance within a
61 tissue, its remodeling, and the onset of mechanotransduction events. Importantly, because
62 there is significant knowledge on the biochemical and mechanical properties of the

63 molecular elements involved, quantitative modelling can be carried out, and quantitative
64 mechanistic predictions can be obtained. This is precisely what this review is focused on:
65 how the molecular clutch concept, and its quantitative predictions, provides a framework
66 to understand how cells respond to mechanical signals like forces or tissue rigidity. Thus,
67 we will not enter in details on the complex molecular regulation of cell/cell and cell/ECM
68 adhesions or the actin cytoskeleton, on which there are excellent recent reviews [25-27].
69 First, we will summarize the molecular pathway that force must follow from actin to
70 integrins/cadherins, and evidence for mechanical tension in the molecules involved. We
71 note that whereas most of the examples and discussion will refer to the better studied case
72 of integrin-based cell-ECM adhesion, the concepts discussed are generalizable to cell-cell,
73 and potentially almost any type of specific adhesion. Second, we will describe the behavior
74 of the clutch model, and how it responds to its main mechanical and molecular parameters.
75 In this regard, we will discuss the fundamental notion that molecular clutch response is not
76 driven by forces per se (which constantly change due to their dynamic nature) but by the
77 force **loading rate**. Third, we will discuss how clutch mechanics couple to mechanosensitive
78 proteins to enable cell mechanoresponse. Finally, we will address implications in cell
79 migration.

80 **Molecular pathways of force transmission through the clutch.**

81 Despite the molecular complexity of cell-ECM adhesions, the fundamental components of
82 a molecular clutch system can be summarized as a) actin filaments, b) myosin motors pulling
83 on actin filaments, c) adaptor proteins, d) integrins/cadherins, and e) extracellular ligands
84 at the ECM or other cells (Fig. 1). Numerous proteins from both the cell-cell and cell-ECM
85 adhesome are potentially involved in force transmission. As to cell-ECM interactions, force
86 is transmitted through: 1) direct interactions between the ECM and integrins [28, 29], 2)
87 adaptor proteins that directly connect integrins to the actin cytoskeleton -including α -
88 actinin [30], filamin [31], tensin [32], kindlin [33] and talin [34-36]- and 3) indirect
89 interactions between integrins and actin –mediated by vinculin [34, 37-39], FAK, paxillin,
90 and Kank [40], among many others-. As to intercellular interactions, an equivalently
91 complex network of adaptors connects cadherins to actin [41]. Recently, some of these
92 adaptors (such as vinculin) have been shown to be shared between cell-ECM and cell-cell
93 interactions [12]. Only a few of the several proteins linking actin to integrins and cadherins
94 have been experimentally verified to be submitted to force, although potentially several
95 more could be. For instance, experiments pulling on integrin-ECM or cadherin-cadherin
96 bonds with magnetic tweezers, or measuring tension on ECM ligands through fluorescence
97 reporters or tension gauges (that dissociate above a given force) have shown that integrins
98 [29, 42-47] and cadherins [48-51] withstand forces. Besides, fluorescence tension probes
99 have confirmed with piconewton resolution that not only integrins [52, 53] and cadherins
100 [54] are under force but also intracellular proteins like vinculin [37] and talin [35, 36] in cell-
101 matrix adhesions, and alpha-catenin [55] in cell-cell adhesions.

102

103 **Regulation of force transmission through the clutch**

104 The fundamental property of the molecular clutch connecting actin to the ECM is its
105 dynamic nature, i.e., the more engaged the different components are to each other, the
106 more effectively force will be transmitted. However, the interplay between the different
107 elements leads to interesting non-trivial behaviors, which can be understood through
108 mathematical models [56] which initially emerged inspired by the similar and better studied
109 system of muscle contraction. Those models can be in the form of computational
110 simulations [57-60] or analytical solutions [60-63], and all consider the effect of dynamic
111 bonds between a surface and a sliding filament. In the form proposed by Chan and Odde
112 [57], model response rests on two key properties under force of the molecules involved.
113 First, myosin motors will contract actin filaments at a fixed speed (of about 120 nm/s) if
114 their action is unopposed by force [57, 64]. If a force opposes myosin action, its contraction
115 speed will decrease with force until stalling completely if the force applied matches the
116 maximum force that a myosin motor can apply (2 pN) [65]. This inverse relationship
117 between actin speed and force has been widely reported [34, 57, 64, 66], although it is
118 worth noting that a direct relationship has been observed below speeds of 10 nm/s [66],
119 possibly due to changes in myosin density in cell lamellae [67]. Second, as force is
120 transmitted to molecular bonds (actin-adaptor proteins, adaptor proteins-integrins, or
121 integrins-ECM), the lifetime of the bonds will be affected, eventually destabilizing bonds
122 when submitted to sufficiently high forces (see section below for the distinction between
123 **slip and catch bonds**). In most models, only one type of bond is considered, which is
124 assumed to correspond to the weakest link in the actin-adaptor protein-integrin-ECM chain.
125 This “weakest link” has been attributed both to intracellular bonds involving adaptor
126 proteins [57, 68], or to the integrin-ECM link [64, 69, 70]. In any case, the fact that different
127 clutch components show different retrograde flow speeds [18] suggests that all bonds play
128 a role, and that modelled bonds likely reflect an integrated response of the entire clutch
129 rather than a weakest link.

130 In a typical molecular clutch simulation, the system begins with myosin freely contracting
131 an actin filament, containing several adaptor protein-integrin complexes (clutches) which
132 are not bound to the substrate (Fig. 2A-B). With time, clutches begin binding to the
133 substrate according to a given **binding rate**. Once the system is engaged, myosin
134 contractility pulls on the substrate, deforming it if it is compliant and exerting a force which
135 distributes among the different bound clutches. As force keeps on building, bonds
136 eventually fail, leading to a catastrophic event which quickly releases all force and
137 disengages all bonds, allowing the cycle to start again (Fig. 2B-C). Such cycles are termed
138 “**load and fail**” or “**stick-slip**” behavior, and have been observed in neuronal growth cones
139 [57], focal adhesions [71], and the leading edge of mouse embryonic fibroblasts [72, 73].

140 Interestingly, the cycles of force generation are finely regulated by the properties of both
141 the molecular players involved and the cell microenvironment, endowing cells not only with
142 exquisite mechanosensitivity but also with the ability to tune it. The fundamental factor
143 driving clutch mechanosensitivity (and response to both cellular and extracellular
144 parameters) is the force loading rate, i.e. the speed at which force in clutches builds once
145 they engage. This is nicely exemplified in the case of cell response to substrate rigidity, a
146 microenvironmental factor which drives cell differentiation [4] or tumor progression [74],

147 among others. Substrate rigidity directly controls the loading rate, which in simple terms
148 can be understood as the product of the substrate rigidity times the speed of retrograde
149 flow. In clutch models, force transmission is maximized for a specific value of rigidity, or
150 loading rate. Above the optimal rigidity, force in individual clutches loads so fast upon
151 binding that clutches become destabilized and disengage before additional clutches can
152 bind. That is, **unbinding rates** (off rates) become faster than binding rates (on rates), the
153 number of clutches simultaneously engaged drops drastically, and overall force
154 transmission decreases (Fig. 2C-D). This is a regime known as “**frictional slippage**”,
155 characterized by high retrograde flow, low forces, and no load and fail cycles, and observed
156 for instance in neuronal growth cones [57], or the trailing edge of migrating keratocytes
157 [75]. Below the optimal rigidity, force loading becomes so slow that clutches eventually
158 disengage before high forces can be reached. Thus, the molecular clutch model predicts a
159 biphasic relationship between rigidity (loading rate) and force, in which forces first increase
160 and then decrease with rigidity. Such behavior has indeed been observed in neuronal
161 growth cones and glioma cells [57, 76], but in several other systems a monotonically
162 increasing rigidity/force relationship has been reported instead [28, 77-79]. This
163 discrepancy is due to the fact that in many cases, cells grow focal adhesions above a
164 threshold in rigidity (due to talin unfolding, see below). Large adhesions increase integrin
165 clustering, the effective binding rate of the system, and the number of bound clutches,
166 preventing the entry into the frictional slippage regime and maintaining high force
167 transmission [34].

168 Other than rigidity, several cellular and extracellular parameters tune the
169 mechanosensitivity of the molecular clutch. In most cases, the effects can also be
170 understood through the regulation of the loading rate. First, reducing myosin contractility
171 lowers the loading rate. Consequently, in myosin inhibition conditions, reaching the optimal
172 loading rate for force transmission requires a higher substrate rigidity. Therefore, whereas
173 myosin inhibition of course reduces overall contractility, there is a specific range of
174 substrate rigidity in which force transmission can be increased (Fig. 2E). This counter-
175 intuitive prediction, which has been observed experimentally [34], occurs at a rigidity where
176 the loading rate is optimal in myosin inhibited conditions, but too high and already within
177 the frictional slippage regime in control conditions. Second, decreasing ECM ligand density
178 reduces binding sites and therefore overall force transmission (Fig. 2E). However, since
179 myosin contractility is now distributed among less clutches, the loading rate experienced
180 by each molecular clutch increases. In turn, this decreases the substrate rigidity
181 corresponding to the optimal loading rate, and optimal force transmission [34]. Third,
182 altering different parameters at the same time can lead to combined effects that also shift
183 optimal force transmission (Fig. 2E). This can be achieved for instance by binding to the ECM
184 through different integrin types (with different binding and unbinding rates) [64], or
185 simultaneously altering the numbers of myosin motors and available clutches [76, 80].

186 While less well characterized, it is tempting to speculate on how different integrin and focal
187 adhesion regulators could impact molecular clutch behavior. For instance, we recently
188 reported [83] that ZO-1, an adaptor protein normally present in cell-cell adhesions but that
189 can also bind $\alpha 5\beta 1$ integrins [84], increases the binding and unbinding rates of $\alpha 5\beta 1$ to

190 fibronectin. This then fosters the formation of adhesions in a manner consistent with
191 molecular clutch predictions [83]. Other adaptor proteins, such as the recently
192 characterized sharnin [85], shank [86], kank [40], or kindlin [33] also regulate integrin
193 properties and could therefore have similar effects. Finally, it is interesting to note that
194 whereas the effect of rigidity has largely been studied with purely elastic substrates, adding
195 a viscoelastic behavior has a significant effect [81]. In this regard, we have recently shown
196 that cell response to purely viscous environments can also be understood through a
197 molecular clutch mechanism driven by force loading rates [82].

198 **Regulation of force transduction by the clutch**

199 Once we understand how the molecular clutch regulates cell-ECM force transmission, the
200 next pressing question is to determine how force then triggers mechanosensing events, i.e.,
201 how cells convert force into biochemical signals that will eventually affect cell function. This
202 process is generally believed to occur through mechanosensing molecules, in which force
203 alters their conformation and biochemical properties. The best known example is that of
204 the actin-integrin adaptor protein talin, which unfolds under force and exposes binding sites
205 to vinculin [87, 88]. Other proteins such as α -catenin [89] or filamin [90] also change binding
206 partner affinities under force, and force-induced molecular events include changes in
207 integrin conformation [91], ion channel activity [92, 93], or kinase activity [94] (see [3, 95]
208 for recent reviews). However, it is important to note that in the context of a continuously
209 contracting cell, none of these **molecular mechanosensors** is sufficient on their own to build
210 an effective cell mechanosensing mechanism. Taking talin as an example, if a given actin-
211 talin-integrin clutch engages to the substrate, myosin contractility will start pulling on it.
212 This will eventually load force sufficiently to induce talin unfolding, regardless of substrate
213 rigidity or any other external mechanical stimulus.

214 To properly discriminate between different levels of rigidity, a system of at least two
215 mechanosensors with different properties is required. In the case of the actin-talin-integrin-
216 ECM clutch, this is provided by the different properties under force of talin unfolding, and
217 of integrin-ECM binding [34]. Talin unfolding responds to force according to the bell model
218 [13] as a classical slip bond. That is, when a constant force is applied to a single talin
219 molecule, the time required to unfold decreases exponentially with force [88]. In contrast,
220 the binding between $\alpha 5\beta 1$ [96] or $\alpha v\beta 3$ [34, 91] integrins and the ECM protein fibronectin
221 behaves as a catch bond (or more accurately, a catch-slip bond). That is, the time required
222 to break the bond first increases and then decreases with force. This differential behavior
223 leads to a crossover between the two force/lifetime curves, such that for low forces integrin
224 unbinding is faster than talin unfolding, and for high forces the opposite holds (Fig. 3A).
225 Because upon integrin unbinding force would be released and no longer pull on talin, this
226 system effectively triggers talin unfolding only above a force threshold. Talin unfolding then
227 leads to vinculin binding, which in turn triggers focal adhesion growth through mechanisms
228 that are not fully elucidated [38, 97].

229 A relevant nuance is that whereas for simplicity we have referred to force to reason on the
230 differential response of the mechanosensors, as discussed above a molecular clutch system
231 controls force loading rate rather than force itself. However, the dependency of

232 unfolding/unbinding rates on loading rate can be readily calculated if force/lifetime curves
233 are known [98], leading to the same crossover behavior (Fig. 3A). Thus, all the factors
234 described above controlling the loading rate experienced by individual molecules (substrate
235 rigidity, myosin contractility, ECM coating, integrin binding kinetics) will determine not only
236 force transmission but also force transduction, and the activation of downstream signals
237 such as focal adhesion formation, and the nuclear localization of the transcriptional
238 regulator YAP [34, 99]. In the case of rigidity, for instance, talin unfolding only occurs above
239 a given threshold. Subsequent focal adhesion growth (reinforcement) then increases the
240 clutch binding rate, simply because there are more integrins to bind to. This then prevents
241 the decrease in force, and increase in actin retrograde flows, that would be otherwise
242 expected at high rigidities (Fig. 3B-C). Below the rigidity threshold, integrin unbinding
243 (rather than talin unfolding) predominates, as supported by experiments using ECM ligands
244 attached to tension gauge tethers [46]. Other than rigidity, we have recently shown that
245 cell sensing of the nano-scale distribution of ECM ligands, and subsequent formation of
246 focal adhesions, can also be explained by a clutch model considering two differential
247 mechanosensors, and the spatial arrangement of ligands [100].

248 Whereas this clutch-mediated differential mechanosensing mechanism has so far been
249 demonstrated only for the talin unfolding versus integrin-ECM unbinding system, it could
250 apply in several other instances. Potential examples include cadherin/cadherin unbinding
251 versus α -catenin unfolding [89] (in cell adhesions), glycoprotein Ib (GPIb)/von Willebrand
252 factor unbinding versus GPIb unfolding (in platelets) [101], or stretch-induced
253 conformational changes in the actin crosslinker filamin [90], which could add an additional
254 mechanosensor in series with the integrin/talin system. Importantly, the fundamental
255 feature to enable mechanosensitivity is the crossover between lifetimes of the two
256 mechanosensors, and not necessarily slip bond/catch bond behavior per se. Thus, in
257 principle mechanosensitivity could also be achieved with two slip bonds, as long as their
258 sensitivities to force were different.

259 Summarizing, the fundamental parameter that determines the response of a molecular
260 clutch system is the force loading rate, which is sensitive to factors both external (substrate
261 rigidity, ECM or cadherin ligand density) and internal (myosin contractility, type and
262 clustering of integrins), and varies greatly in different physiological conditions [102]. This
263 endows cells with exquisite mechanosensitivity, which results in regulation of both force
264 transmission and in the activation of mechanosensors. Supporting this hypothesis of the
265 loading rate as the key ingredient, experiments have shown that it controls integrin
266 adhesion [103, 104] and focal adhesion formation [105]. Interestingly, this hypothesis also
267 proposes an alternative to an old debate in the field, which is whether cells sense rigidity
268 by applying a given deformation (strain) to the substrate and measuring the resulting force
269 (stress), or vice versa [79, 106, 107]. Measuring force loading rates may be more optimal
270 than measuring forces or deformations per se, for two fundamental reasons. First and as
271 noted theoretically [108, 109], if time dependency (and loading rate) is ignored, the
272 magnitude of force that cells can apply depends on their contractility but not necessarily on
273 the mechanical properties of the cell environment, precluding proper mechanosensing.
274 Second, cell-applied forces continuously fluctuate, as observed at scales ranging from cell

275 collectives [110], to focal adhesions [71], to local 100 nm-scale contractions in the leading
276 edge of fibroblasts [111]. In fact, molecular clutch mechanisms driven by loading rates have
277 been proposed to explain force fluctuations at the level of cell collectives [5] and focal
278 adhesions [112]. The mechanics of nano-scale contractions, which are associated with
279 altered response to substrate rigidity [113], and altered activity of receptor tyrosine kinases
280 [114], is less clear. However, both the contractions and the trigger of mechanosensing
281 events affecting kinase activity may also be controlled by the loading rate.

282 **Regulation of cell migration by the clutch.**

283 Since the clutch model predicts cell-substrate forces, one could think that this can directly
284 explain cell migration. Yet, cells generate tractions that are orders of magnitude higher than
285 those needed to migrate, and tractions generated by a migratory single cell add up to zero
286 within measurement noise [115]. Tractions should thus not be interpreted as propulsion
287 forces. However, tractions are linked to migration speed through the retrograde flow [14,
288 16, 22]. For a given actin polymerization rate, cells exhibiting the slowest retrograde flow -
289 and therefore the highest traction- should be the ones that migrate faster. This relationship
290 is well captured by early clutch models, which focused only on dynamics of the leading edge
291 [57]. A more general formulation of cell migration in terms of clutch models requires not
292 only taking into account the leading edge, but also how all protrusions pull on the cell body.
293 Such formulation was accomplished by Bangasser et al [76], who showed that a generalized
294 clutch model predicts an optimal rigidity for migration as a function of the number of
295 clutches and motors. These predictions were successfully tested for neurons and glioma
296 cells, which exhibit a biphasic behavior of their migratory properties [76]. We note,
297 however, that these cells do not exhibit adhesion reinforcement, so the general ability of
298 clutch models to predict a relationship between migration speed and rigidity needs to be
299 further assessed.

300 Besides contributing to understand single cell migration, clutch models have also been
301 successful at explaining collective **durotaxis**, this is, the ability of groups of cells to follow
302 gradients of rigidity [5]. When a group of epithelial cells was seeded on a substrate with a
303 rigidity gradient, cells moved preferentially towards the stiff area of the substrate.
304 Collective durotaxis was lost when force generation was inhibited with Blebbistatin and
305 when cell-cell junctions were abrogated. Traction maps revealed that cells exerted inward
306 forces of same magnitude but opposite sign only at the two edges of the monolayer. This
307 force pattern implies long range force transmission through cell-cell junctions. To explain
308 collective durotaxis, we modelled the cell monolayer as a contractile continuum adhered to
309 the substrate through two clutches located at the stiff and soft edges. Force balance implies
310 that cells on soft and stiff areas of the substrate generate the same force, and therefore
311 cell-matrix adhesions are subjected to the same loading rate. The model then predicts that
312 dynamics at both edges are identical but that substrate displacement is larger on the soft
313 edge than on the stiff one. As such, contraction of the monolayer systematically shifts the
314 center of the cell cluster, thereby resulting in durotaxis. This simple model, designed to
315 explain collective durotaxis, is also applicable to single cell durotaxis [116], which is
316 predicted to be more efficient for cells that are large and highly contractile.

317

318 **Concluding remarks.**

319 The dynamic nature of the cytoskeleton and adhesion complexes has long been
320 acknowledged, and the molecular clutch concept has demonstrated to be a useful
321 framework to understand the underlying mechanisms. Further, recent developments have
322 shown that quantitative modelling of the different molecular elements in the clutch
323 provides a powerful tool to predict how cells detect cues from their environment, and
324 respond by tuning their migration, but also adhesive and signaling events. However, several
325 outstanding questions remain open (see outstanding questions box). First, how force is
326 transmitted and distributed through the very complex molecular assemblies at cell-matrix
327 and cell-cell adhesions (i.e., which adaptor molecules are directly submitted to force, and
328 to what degree) remains largely unknown. Addressing this question, and understanding the
329 force-induced molecular events involved, will enable the refining of clutch models to predict
330 cell response in a much more general way. Second, it is highly likely that dynamic clutch-
331 like adhesion occurs not only at cell adhesions but also throughout cells, for instance in
332 cytoskeletal-nuclear coupling. Exploring such events and their implications is also a major
333 area of exploration. Finally, whereas the molecular clutch concept has been largely explored
334 in cells seeded on flat two-dimensional substrates, the interaction between actin structures,
335 myosin, and adhesive complexes is known to be largely affected by the three-dimensional
336 setting found in most physiological conditions. Whereas the effect of this three-dimensional
337 setting in the molecular clutch concept have begun to be explored [19], its implications
338 remain largely uncharted. Addressing these and other open questions is thus likely to lead
339 to new exciting developments in the coming years.

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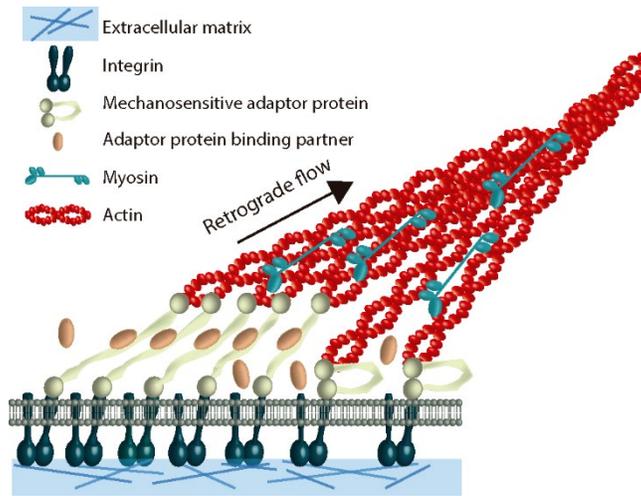
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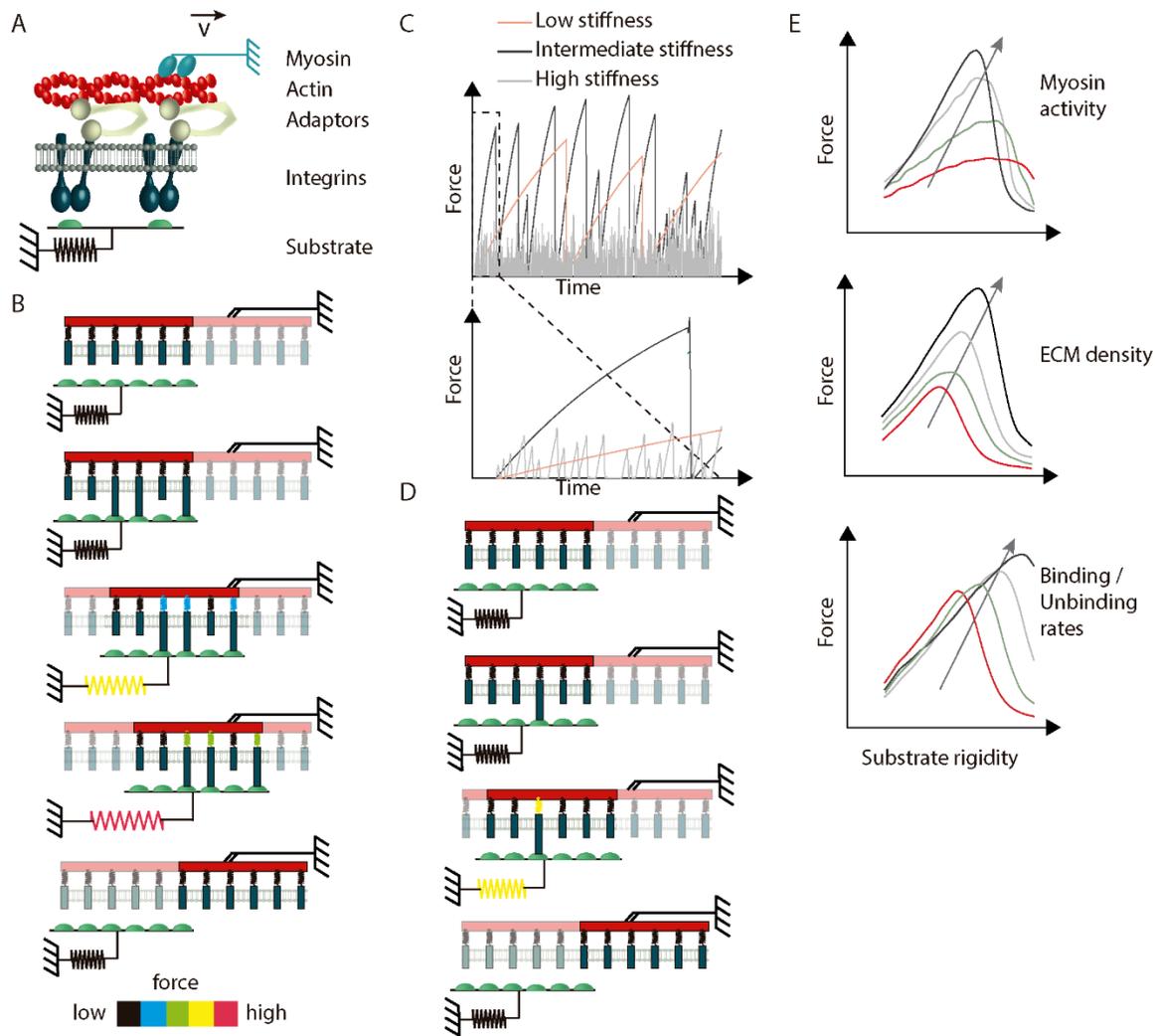
574 **Figure legends**



575

576 **Figure 1.** Cartoon depicting the serial connection between the extracellular matrix,
577 integrins, mechanosensitive adaptor proteins, and actin. As myosin pulls on actin filaments,
578 force is transmitted to the different elements, leading to conformational changes in adaptor
579 proteins and affecting unbinding events.

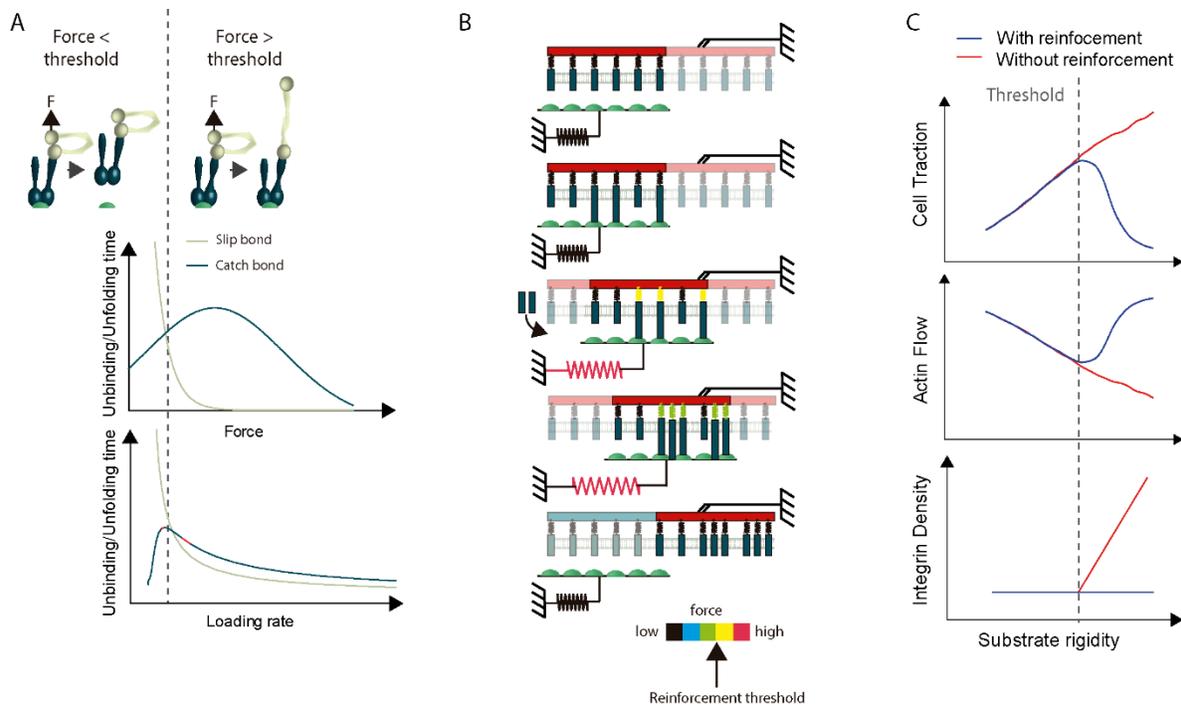
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582 **Figure 2.** Force transmission through the molecular clutch. A) Cartoon summarizing the
 583 fundamental elements of the system. B) From top to bottom, sequence of events in a typical
 584 “load and fail” cycle of a molecular clutch (rectangles represent integrins). As clutches bind,
 585 myosin contractility deforms the substrate, building force on the substrate and each bound
 586 clutch. At some point, force leads to bond de-stabilization, all clutches disengage, and the
 587 cycle starts again. C) Typical plots of force exerted versus time for molecular clutches on
 588 low, intermediate, and high rigidity. D) From top to bottom, sequence of events in a typical
 589 “frictional slippage” cycle of a molecular clutch, observed on a high-rigidity regime. As a
 590 clutch binds, myosin contractility builds force very quickly due to the high rigidity, leading
 591 to clutch disengagement before others have time to bind. This limits overall force
 592 transmission to the substrate. E) Clutch model predictions of average force transmission to
 593 the substrate as a function of substrate rigidity. Top, middle, and bottom graphs show the
 594 changes in the curve induced by increasing myosin activity, increasing ECM ligand density,
 595 and simultaneously increasing binding and unbinding rates, respectively.

596



597

598 **Figure 3.** Force transduction through the molecular clutch. A) bottom, effect of either a
 599 constant force or a constant force loading rate on the average times required for protein
 600 unfolding or bond unbinding. Typical curves for a slip or catch bond are shown. Top,
 601 expected effect on a system in which force is applied to a serial link between a molecule
 602 that unfolds as a slipbond (such as talin) and a bond that unbinds as a catch bond (such as
 603 an integrin-fibronectin bond). Unbinding occurs first when force is below the threshold, and
 604 unfolding (and subsequent mechanotransduction) occurs first when force is above the
 605 threshold. B) From top to bottom, sequence of events in a typical “load and fail” cycle of a
 606 molecular clutch including mechanotransduction (reinforcement) events. As clutches bind
 607 and force builds, some clutches surpass the threshold force required for
 608 mechanotransduction, leading to the recruitment of additional integrins. This increases the
 609 number of bound clutches, reducing the force applied per clutch, delaying the failure of the
 610 system, and increasing average force transmission. C) Examples of predicted force/rigidity
 611 curves in the presence and absence of reinforcement. Reinforcement only affects force
 612 transmission above a threshold in rigidity, which corresponds to the loading rate threshold
 613 from panel A. Then, the increase in integrin recruitment prevents the reduction in force
 614 (and increase in actin flows) normally expected in a molecular clutch system.

615

616 **Glossary**

617 **Adaptor proteins:** term usually employed to refer to the proteins linking actin to either
618 integrins or cadherins in cell/matrix or cell/cell adhesion complexes, respectively.

619 **Binding/unbinding rates:** For a given binding event (such as an integrin-ECM bond),
620 inverse of the average time required to bind/unbind the bond, respectively. Whereas
621 binding occurs at zero force, unbinding rates depend on the force applied to the bond.

622 **Catch bond:** More precisely defined as a catch-slip bond, a catch bond is a bond in which
623 unbinding rates decrease with applied force up to a given threshold, and then increase.
624 Catch bonds thus have an optimal stability (minimum unbinding rate) when a specific
625 value of force is applied to the bond. Importantly, this concept can also be applied to
626 molecular events other than unbinding, such as protein unfolding.

627 **Cell contractility:** Ability of a cell to contract its actin cytoskeleton via myosin motors. In a
628 situation with very low cell adhesion, contractility would power fast retrograde flows. In a
629 context of high adhesion, contractility is transmitted to the substrate, leading to cell-
630 matrix (or cell-cell) force transmission.

631 **Durotaxis:** Directional cell migration towards areas of increased substrate rigidity.

632 **Frictional slippage:** Regime with low cell-matrix adhesion in which transient clutch
633 engagement is unable to significantly slow retrograde flow.

634 **Load and fail/stick slip:** Regime with high cell-matrix adhesion in which simultaneous
635 engagement of several clutches leads to repeated cycles of progressive buildup of force,
636 followed by complete disengagement and force release.

637 **Loading rate:** In units of force/time, rate at which applied force increases for a given
638 clutch or clutch ensemble.

639 **Molecular clutch:** link between actin and an ECM ligand (or a neighboring cell) which can
640 be bound (engaged) or unbound. Usually assumed to represent the serial link between
641 actin, an individual adaptor protein, an integrin, and an ECM ligand.

642 **Molecular mechanosensor:** Molecule that responds to force application in any way
643 (domain unfolding, unbinding from ligands, conformational changes, or others).

644 **Retrograde flow:** Movement of actin filaments from the edge towards the center of cells.
645 It can be powered by myosin contractility, actin polymerization, or both. It is important to
646 note that in the context of a migrating cell, the relevant flow that drives force
647 transmission to the substrate is the one measured with respect to substrate (and not cell)
648 position.

649 **Slip bond:** bond in which unbinding rates increase monotonically with applied force.
650 Importantly, this concept can also be applied to molecular events other than unbinding,
651 such as protein unfolding.

652 **Outstanding Questions Box**

- 653 • How is force transmitted across the complex molecular assemblies at cell-cell and
654 cell-matrix adhesions, what are the corresponding force-induced molecular events,
655 and how can they be introduced in molecular clutch models?
- 656 • Do clutch-like adhesive mechanisms take place outside of cell adhesions, such as in
657 nuclear-cytoskeletal links?
- 658 • How is the molecular clutch concept affected by the 3D distribution of cytoskeletal
659 and adhesive structures in physiological scenarios?

660 **Trends Box**

- 661 • By considering the molecular and mechanical properties of actin filaments, myosin
662 motors, adaptor proteins and integrins/cadherins, the molecular clutch model can
663 quantitatively predict cell response to internal and external mechanical factors.
664
- 665 • Those factors include cell contractility, matrix rigidity, and the density, nature, and
666 distribution of matrix ligands, and affect cell response largely by controlling the rate
667 of force loading in specific molecules.
668
- 669 • Due to its dynamic nature, clutch-mediated mechanosensing requires force
670 application to at least two molecular mechanosensors in series, with differential
671 response to force.
672
- 673 • The type of cell responses involved so far in clutch-mediated mechanosensing include
674 cytoskeletal dynamics, the growth of cell adhesions, the nuclear localization of
675 transcriptional regulators, and cell migration.

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