

A Current-Mode Interface Circuit for a Piezoresistive Pressure Sensor

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Abstract— An interfacing circuit for piezoresistive pressure sensors based on CMOS current conveyors is presented. The main advantages of the proposed interfacing circuit include the use of a single piezoresistor, the capability of offset compensation, and a versatile current-mode configuration, with current output and current or voltage input. Experimental tests confirm linear relation of output voltage versus piezoresistance variation.

Index Terms— CMOS analog integrated circuit, current conveyor, current mode, interface circuit, pressure sensor.

I. INTRODUCTION

DURING the last few years, integrated pressure sensors on silicon substrate are of growing interest because of their compatibility with CMOS technology. The main advantages of these systems are their improved sensitivity, small size, and cost effectiveness. Silicon pressure sensors that utilize the piezoresistive effect are usually based in a four-element Wheatstone bridge configuration, formed by two R_p^+ elements (their resistance increases with pressure) and two R_p^- elements (their resistance decreases with pressure). The output voltage of such a transducer is sensed by an interface circuit usually based on operational amplifiers [1]. In these four-element pressure sensors, accurate resistance matching between R_p^+ and R_p^- and equal variation of absolute resistance with pressure are two essential characteristics for proper operation to reduce the offset and increase the sensitivity of the sensor. These constraints complicate the technological process to implement R_p^+ and R_p^- elements.

The use of a single piezoresistance element eliminates the need to match closely the four resistors that form the Wheatstone bridge design [2]. A novel cost-effective current-mode interfacing circuit designed to operate with input from a single piezoresistance element is presented in this paper. The proposed circuit, based on second-generation current conveyors (CCII+) [3], also offers current output which can be very useful in a number of applications in which relatively long wires are used to connect the sensor to the monitoring system. Such is the case in biomedical systems where the proposed configuration is to be used. The pressure sensor integrated on the chip with the proposed interfacing circuit forms a sensing

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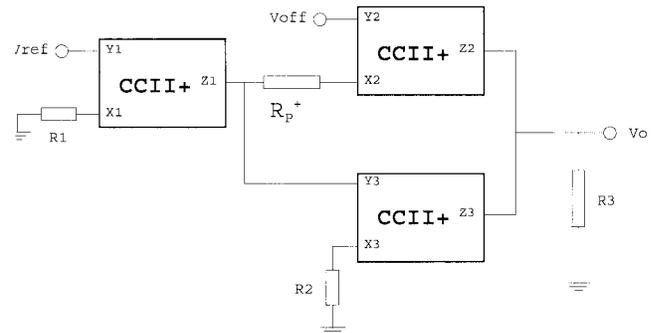


Fig. 1. Block diagram of the interface circuit. Piezoresistance is denoted by $R_p^+ = R_{p0}^+(1+x)$.

element. Such an element may be directly connected to the external patient-monitoring system with increased signal-noise immunity and transmission efficiency.

II. CIRCUIT DESCRIPTION

The second-generation current conveyor CCII+ is a known current-mode three-port analog building block with the following characteristics: $V_x = V_y$, $I_x = I_z$, and $I_y = 0$ [3]. The proposed interface involves three such CCII+ cells, three conventional resistors R_1, R_2, R_3 (the last one at the monitoring instrument side), and a single piezoresistor, denoted as $R_p^+ = R_{p0}^+(1+x)$, where R_{p0}^+ is the resistance at reference pressure and $x = \Delta R/R_{p0}^+$ is the relative change proportional to pressure variation. The resulting circuit schematic diagram is depicted in Fig. 1.

A current source configuration is obtained via the first CCII+. This current value I_{z1} is equal to I_{x1} and therefore determined by reference voltage V_{ref} and resistance R_1 . The applied pressure produces an absolute change ΔR in the piezoresistor R_p^+ . The small change in piezoresistor value affects the voltage at node $Z1$

$$\begin{aligned} V_{z1} - V_{off} &= I_{z1} R_p^+ \\ V_{z1} &= I_{z1} R_{p0}^+(1+x) + V_{off} \\ &= \frac{V_{ref}}{R_1} R_{p0}^+(1+x) + V_{off}. \end{aligned} \quad (1)$$

According to the CCII+ operation, the output current of the second CCII+ also follows the input current ($I_{z2} = -I_{x1}$) since $Y3$ is a high impedance node and does not affect the value of the current through the piezoresistor. On the other hand, the output current of the third CCII+ will be controlled by V_{z1} and R_2 ($I_{z3} = V_{z1}/R_2$). The two currents I_{z2} and I_{z3} are then added to obtain the output current I_o and,

consequently, the output voltage will be

$$V_o = (Iz_3 - Iz_2)R_3. \quad (2)$$

Therefore, a linear dependence between the output current I_o and the relative piezoresistor variation x is obtained and can be expressed as follows:

$$\begin{aligned} I_o = Iz_3 = Iz_2 &= \frac{V_{z1}}{R_2} - \frac{V_{\text{ref}}}{R_1} \\ &= V_{\text{ref}} \frac{R_{p0}^+}{R_2 R_1} x + \frac{V_{\text{ref}}}{R_1} \left(\frac{R_{p0}^+}{R_2} - 1 \right) + \frac{V_{\text{of}}}{R_2}. \end{aligned} \quad (3)$$

In order to eliminate the constant output offset value formed by the last two terms, either R_2 has to be matched with the initial piezoresistor value R_{p0}^+ and $V_{\text{off}} = 0$, or it could be also compensated by an appropriate external voltage applied to the input V_{off} . Then, after the output offset value correction, the final output value is

$$I_o = V_{\text{ref}} \frac{R_{p0}^+}{R_1 R_2} x = kx. \quad (4)$$

A current output proportional to the pressure variation is obtained while the resistors' ratio R_3/R_1 may be used to control the output voltage gain of the compensated circuit. It should also be noted that both reference and offset inputs are high impedance nodes and therefore are practically not affected by the length of connection wires, although V_{ref} may be also integrated with this circuit. Moreover, the proposed configuration can be used in a true current-mode operation with current reference input at node x_1 and current output, and this is difficult to obtain with operational amplifiers.

III. EXPERIMENTAL RESULTS

The proposed circuit of Fig. 1 has been implemented using CMOS current conveyors cells previously fabricated in an 1.2- μm CMOS process [4]. Experimental results were obtained using a typical piezoresistance (with $R_{p0}^+ = 2.391 \text{ k}\Omega$) with a 10% variation due to pressure changes [5]. The experimental fixed resistance values were set to $R_1 = 2.395 \text{ k}\Omega$, $R_2 = 2.393 \text{ k}\Omega$, $R_3 = 23.926 \text{ k}\Omega$ (in order to set the gain factor to 10). Reference voltage is fixed at $V_{\text{ref}} = 0.209 \text{ V}$ and an offset compensation is applied at $V_{\text{off}} = -2.24 \text{ mV}$. A typical experimental measurement set for the proposed circuit and its linear regression are shown in Fig. 2. A linear dependence of output V_o versus resistance variation x is obtained. The nonlinearity measured using a best fit straight-line for absolute minimum squared error is less than 1% (full scale output). Furthermore, the whole interfacing circuit provides a relatively good frequency response up to 250 kHz.

IV. CONCLUSION

A novel configuration for a pressure sensor interfacing circuit based on CMOS current conveyors has been designed and tested. This circuit uses a single piezoresistive element, thus avoiding the problems of the traditional four-element pressure sensors related to the matching between R_p^+ and R_p^- piezoresistances. Monolithic implementation of the pressure sensor plus the interface circuit in a single chip is currently

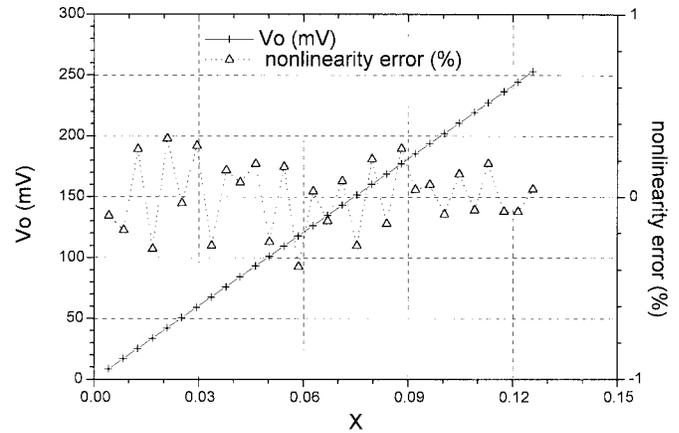


Fig. 2. Circuit output voltage and linearity error versus piezoresistor variation rate $x = \Delta R/R_{p0}^+$.

in progress. This interface circuit is well suited for surgical cardiovascular applications for accurate intravascular pressure measurements. The pressure sensor plus this electronic interface circuit fulfill specific characteristics: minimum number of wires, minimum power dissipation, high noise immunity of the signal transmission, and accurate pressure–voltage conversion.

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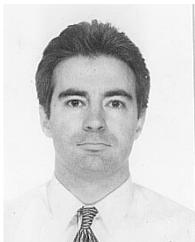
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